Optimal Assignment and Relocation of Shared Autonomous Vehicles Considering Mode Choices

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1 **Introduction**

It is predicted that Autonomous Vehicles (AVs) will enter the global vehicle market in the next few decades. The expected benefits associated with AVs, including increased safety and reduced traffic and parking congestion, may not be significant unless the vehicles become affordable and common (Litman, 2017). In the meanwhile, sharing mobility services will continue to grow, which greatly improves the vehicle and parking utilization rates. Therefore, it is desirable to develop efficient Shared Autonomous Vehicle (SAV) systems to make AVs more affordable and accessible.

In the SAV systems, operators need to make efficient operational decisions to meet the needs 9 of travel demand in both spatial and temporal dimensions. Efficient vehicle operations aim to 10 generate high profits. Meanwhile, it also requires a high level of service to attract sufficient 11 demand requests. Compared to Conventional Private Vehicles (CPVs), the mobility services 12 provided by efficient SAV systems may be more convenient and flexible thanks to self-driving 13 technologies. This paper focuses on the optimal assignment and relocation problem of SAV 14 systems, while the competitions between SAVs and CPVs are explicitly modeled by a discrete 15 choice model, in which the attributes such as travel time, travel cost, and level of service are 16 considered to determine the market share of SAVs. 17

Many studies have been conducted in the field to address the dispatching, fleet sizing, and 18 pricing problems in vehicle sharing operations. Most of them focus on the vehicle relocation 19 problem. The relocation of shared vehicles can be completed actively by relocation staff opera-20 tions (e.g., Kek et al., 2006) or passively by adopting pricing strategies to influence demand (e.g., 21 Barth et al., 2004 and Xu et al., 2018). The demand for transportation modes can be influenced by 22 many factors. The elastic demand has been considered in the car-sharing literature, which mainly 23 focus on the effectiveness of pricing strategies to rebalance the system (e.g., Jorge et al., 2015). 24 These studies consider the influence of pricing on car-sharing demand in car-sharing relocation 25 problems. There is a limited number of empirical studies that consider the impact to demand 26 from other factors such as travel time. Catalano et al. (2008) applied the multinomial logit (MNL) 27 model that revealed the competition of car-sharing service with private vehicles, carpooling, and 28 public transit. Zhou and Kockelman (2011) also adopted the MNL to predict the likelihood of 29 choosing car-sharing as a travel mode among the existing ones. However, there are few studies 30 using the passive relocation examine the effect of factors other than pricing. For example, Huang 31 et al. (2018) study an optimal station location problem of car-sharing with mode choice and non-32 linear demand affected by travel time. In our study, we take into account the impacts from travel 33 costs, travel times, and level of service to SAV demand. The level of service is represented by the 34 availability of vehicles and availability of parking spaces. 35

36 2 Methodology

³⁷ We examine the vehicle assignment and relocation problem for one-way SAV systems. To deter-

³⁸ mine the optimal vehicle assignment and relocation plan, we propose a time-space network flow

³⁹ model, which is formulated as a non-linear mixed-integer program. A binary logit discrete choice

⁴⁰ model is incorporated into the optimization program to capture travelers' mode choices between

SAVs and CPVs. The proposed non-linear mixed-integer program is computationally challeng-1 ing and expensive. To make this problem tractable, we first reformulate the original model to 2 make the logarithmic functions the only non-linear constraints. A piece-wise linear approxi-3 mation method is developed to linearize the non-linear constraints. Furthermore, the number 4 of break-points has significant effects on the solution quality and efficiency. More break-points 5 leads to a tighter linear approximation so that the piece-wise linear function can have any degree 6 of accuracy (see, e.g., Wang and Lo (2010); Liu and Wang (2015); Wang et al. (2015)). However, 7 introducing a large number of break-points will significantly increase the computation burden. 8 Therefore, the proper break-points should be carefully selected to achieve a good approximation 9 within an acceptable computation time. We propose a dynamic programming to determine the 10 optimal break-point selections. By applying this approach, we show that the proposed solution 11 approach can improve the approximation accuracy without increasing too much computation 12 requirement. 13

14 3 Main Results

¹⁵ We apply our approach to real-world cases based on the city of Singapore collected from a car-¹⁶ sharing company BlueSG. In this data set, a total of 10 stations are selected. We set the SAV ¹⁷ fleet size from 100 to 400 and the demand from 1000 to 5000 in order to create 20 scenarios. For ¹⁸ each scenario, five demand instances are generated from a given probability distribution using ¹⁹ simulation. Our numerical findings are summarized as follows:

The computational results show our approach can consistently produce satisfactory solutions in all instances. We use a case with four times evenly distributed break-points as the benchmark. By using the dynamic programming, the largest objective value gap between our approach and the benchmark is less than 1%. Moreover, the computation time of our approach reduced by 90 % compared with the time of the benchmark on average.

Under our optimal assignment and relocation policies, there is more relocation activities
 when the demand pressure is moderate. Consequently, it leads to a high fulfillment rate and
 market share of SAVs. Few relocations have been conducted when the demand pressure is
 extremely low or high.

We replace the SAVs in the original problem with the Shared Conventional Vehicles (SCVs) to study the impact of vehicle types. SAV services of high price may have a high fulfillment rate when the demand pressure is high. In both median and low price cases, the SCV systems show less vehicle utilization. When the demand pressure is extremely low or high, the gap between cases with SAVs and SCVs is small.

After considering the daily cost of SAVs in the objective function, the maximum profit is
 achieved when the total demand is 10 to 15 times the SAV fleet size. A moderate demand
 pressure is the most suitable for SAV systems. Too high or too low demand will lead to a
 decrease in profits.

• We generate different demand sets to study the influence of city size and travel distance distribution. The SAV services have less fulfillment rate and less market share in a larger city. Nevertheless, demand sets with more short travel requests lead to a higher fulfillment
 and lower utilization of SAV systems.

We test the impact of demand symmetry to SAV systems. There are more relocation ac tivities when the demand is asymmetric compared to symmetric ones in all scenarios. But
 the traffic efficiency is still not as good as that under symmetric demand. Given the same
 demand quantity, the profit under an asymmetric demand set is lower than under a symmetric case.

8 4 Conclusion

In this paper, we address the optimal SAVs operation problem with competition from CPVs. We 9 propose a solution approach for solving the original model. A piece-wise linear approximation 10 method is developed to linearize the non-linear constraints. Further, a dynamic programming 11 is developed to select optimal break-points. We show that the proposed solution approach can 12 consistently and efficiently obtain optimal solutions through quantitative computational experi-13 ments. With optimal assignment and relocation decisions, the SAVs may outperform the CPVs. 14 Numerical results reveal that when the demand pressure is moderate, SAVs can achieve a higher 15 fulfillment rate and market share due to more relocation activities. Furthermore, we study the 16 optimal fleet size and find that the maximum profit is achieved when the demand pressure is 17 moderate. We also evaluate the influence of demand patterns as well as city sizes. The results 18 show that SAV services may be preferable in a small size city with more short-distance and 19 asymmetric travel demand. We may extend this work in future studies by considering stochastic 20 nature in transportation systems or a dynamic case. 21

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